

Alignment and calibration methods for the Belle II TOP counter

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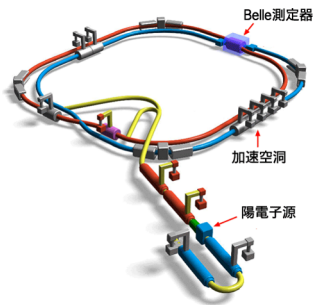
Belle II collaboration



Jožef Stefan Institute, Ljubljana

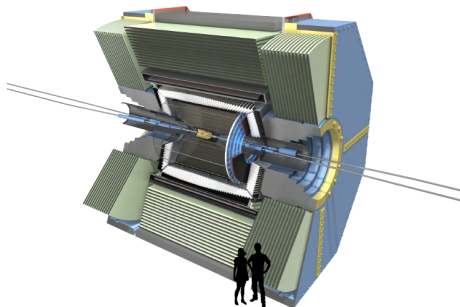
RICH 2016 - Bled, Slovenia

- Successor of Belle experiment (KEK, Tsukuba, Japan)



SuperKEKB accelerator

- upgraded KEKB
- luminosity $40 \times$ KEKB
($8 \times 10^{35} \text{cm}^{-2} \text{s}^{-1}$)
- nano-beam optics



Belle II detector

- upgraded Belle detector
- majority of components replaced



Belle II environment

Critical issues at $\mathcal{L} = 8 \times 10^{35} \text{cm}^{-2} \text{s}^{-1}$

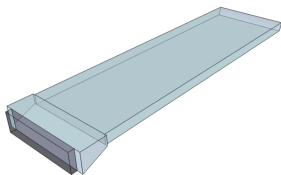
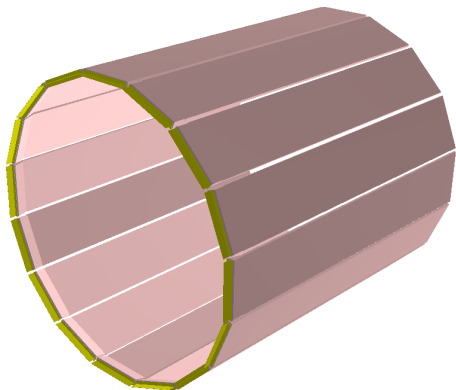
- Higher background ($\times 10 - 20$)
 - radiation damage and occupancy
 - fake hits and pile-up noise in EM calorimeter
- Higher event rate ($\times 40$)
 - affects trigger, DAQ and computing

Have to employ and develop new technologies to make such an apparatus work efficiently.

→ one of such technology is the Time-Of-Propagation (TOP) counter.
(talks by J. Fast and K. Suzuki)

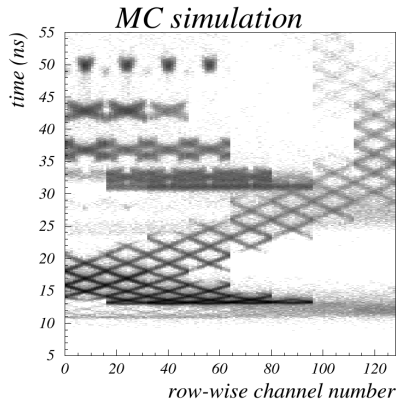
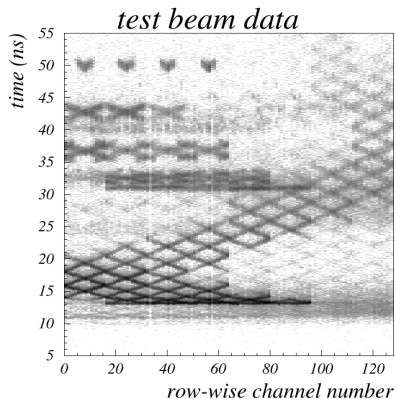
Belle II TOP counter

- 16 modules at $R = 120$ cm covering polar angles $32^\circ - 120^\circ$
 - Quartz bars:
 - 2×45 cm² in cross section
 - 2.6 m long
 - Spherical mirrors:
 - radius of curvature: 6.5 m
 - Expansion prisms:
 - 100 mm long, 51 mm high
 - MCP-PMT:
 - Hamamatsu R10754
 - 2 rows of 16 per module
- talk by K. Matsuoka
- Wave-sampling electronics
- talk by G. Varner



TOP counter response

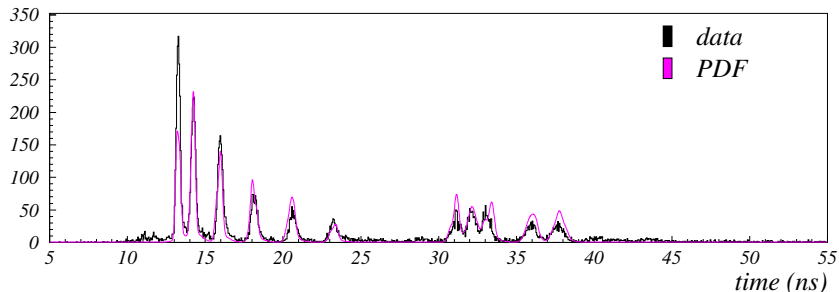
- Ring image consists of complicated patterns
 - depends on particle impact position, angle and velocity



Perpendicular impact of a narrow 2.1 GeV/c positron beam
(data obtained at Spring-8 facility in Japan)

Particle identification: using extended likelihood method

Time distribution in a single channel

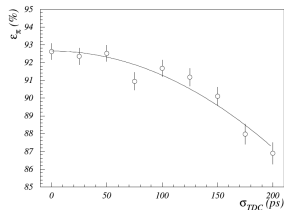


- PDF in a single channel described with a series of Gaussian distributions
 - positions, widths and normalizations determined analytically
 - method presented at RICH2010 (NIM A 639 (2011) 252-255)

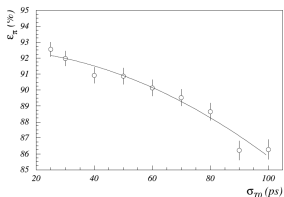
Critical parameters

- single photon time resolution < 100 ps
 - TTS: 35 ps core Gaussian sigma (70%) + ~ 1 ns long tail
 - electronic jitter ~ 50 ps
 - channel offsets aligned to < 50 ps
- start time (T0) jitter < 50 ps
 - bunch length: 6 mm $\rightarrow 20$ ps
 - TOF estimate uncertainty: 5 ps (from extrapolated track)
 - T0 calibrated to 5 - 10 ps precision
- module alignment better than extrapolated track precision
 - position: < 1 mm
 - rotation angles: < 1 mrad

MC study: $B^0 \rightarrow \pi^+ \pi^-$
electronics jitter



T0 jitter



NIM A766 (2014) 237

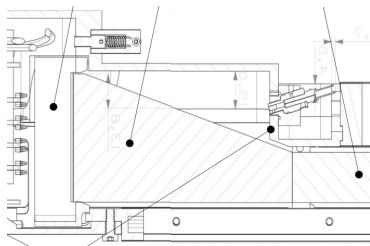
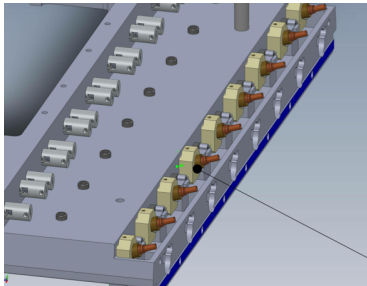
To be presented

Methods for

- calibration of channel offsets
- module alignment
- real time T0 calibration

Calibration of channel offsets

- Dedicated pico-second laser calibration system incorporated into each module, consisting of 9 light sources (fibers) that illuminate MCP-PMT's from the slanted prism side.

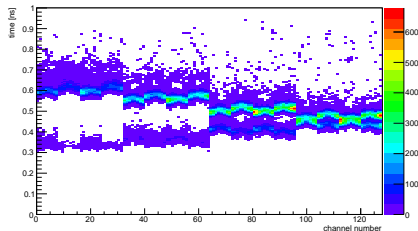


→ poster by U. Tamponi

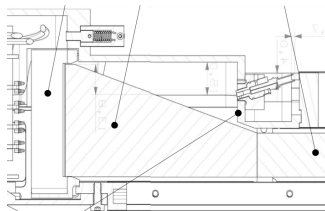
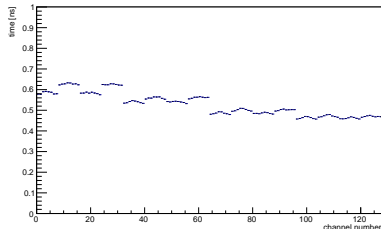
Calibration of channel offsets

- MC simulation: photon propagation times

Photon propagation times vs. channel number



Average propagation time vs. channel number

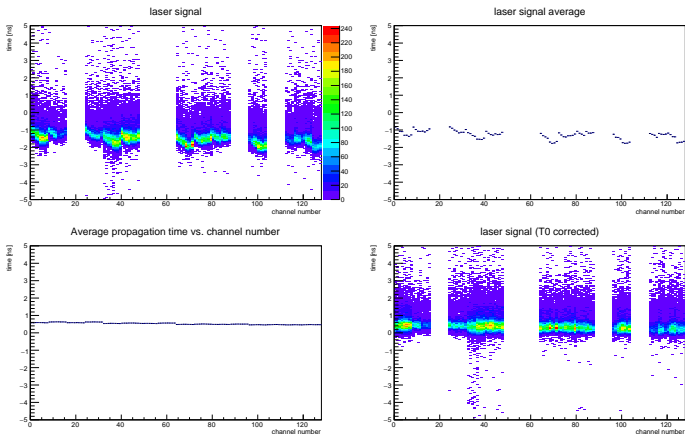


A robust method:

- align average of the measured distribution in each channel with the simulated propagation time average
- needs good knowledge of the fiber light angular distribution

Calibration of channel offsets

- Commissioning data example (preliminary)
 - offset = measured average - simulated one



→ work is ongoing, more refined methods on the way

Alignment

- Alignment of a module
 - find small displacements from its nominal position
 - shifts in x , y and z by $\Delta\vec{r} = (\Delta x, \Delta y, \Delta z)$
 - rotations around x , y and z by α , β and γ

- Positioning of a module:

- first displace it:

$$\vec{r}' = R_z(\gamma)R_y(\beta)R_x(\alpha)\vec{r} + \Delta\vec{r}$$

(going from local to nominal frame)

- then position the displaced module to its place in the barrel

$$\vec{r}'' = R_z(\phi)(\vec{r}' + \vec{d}), \quad \vec{d} = (0, R, z)$$

(going from nominal to Belle II frame)

Alignment: method

- Most suitable are di-muon events: $e^+e^- \rightarrow \mu^+\mu^-$
 - clean, low multiplicity events
 - two high momenta particles ($p > 3 \text{ GeV}/c$)
 - known particle identity (muons)
- Free parameters: 3 shifts, 3 rotation angles, and start time offset t_0
- Minimize the sum of negative log likelihoods over many muons

$$\chi^2 \equiv -2 \sum_{i=1}^n \log \mathcal{L}_{\mu}^{(i)}(\hat{\rho}) = \min, \quad \hat{\rho} \equiv (\Delta x, \Delta y, \Delta z, \alpha, \beta, \gamma, t_0)$$

where $\log \mathcal{L}_{\mu}(\hat{\rho})$ is calculated with our standard extended likelihood method using analytic PDF.

- Minimization can be done with MINUIT, however an iterative procedure similar to Kalman filter would be more suitable

Alignment: iterative procedure

Such iterative procedure can be derived in the following way:

- Suppose we have already minimized χ^2 using i muons:
→ vector of parameters $\hat{\rho}^{(i)}$ and corresponding error matrix $V^{(i)}$
- Taking the next muon we can write:

$$\chi^2 \equiv -2 \log \mathcal{L}_\mu^{(i+1)}(\hat{\rho}) + \Delta \hat{\rho}^T V_{(i)}^{-1} \Delta \hat{\rho} = \min$$

- Expand the first term into Taylor series up to the second order:

$$f(\hat{\rho}^{(i)} + \Delta \hat{\rho}) = f(\hat{\rho}^{(i)}) + \sum_j \frac{\partial f}{\partial \hat{\rho}_j} \Delta \hat{\rho}_j + \frac{1}{2} \sum_{j,k} \frac{\partial^2 f}{\partial \hat{\rho}_j \partial \hat{\rho}_k} \Delta \hat{\rho}_j \Delta \hat{\rho}_k$$

where $f(\hat{\rho}) \equiv \log \mathcal{L}_\mu^{(i+1)}(\hat{\rho})$,

- and solve minimization problem analytically.

Alignment: iterative procedure

- Solution is the following iterative procedure:

$$U^{(i+1)} = U^{(i)} - D^{(i)}$$

$$V^{(i+1)} = [U^{(i+1)}]^{-1}$$

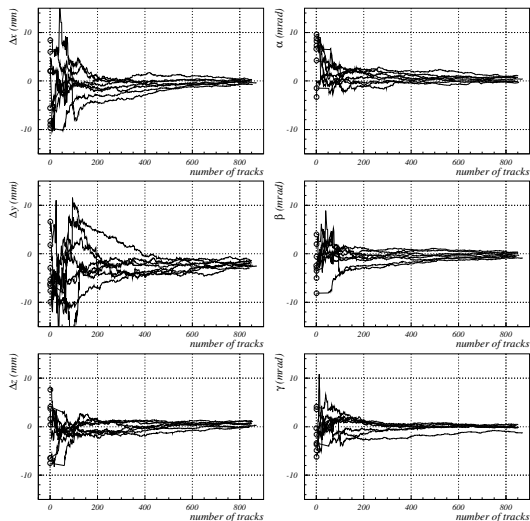
$$\Delta \hat{p} = V^{(i+1)} \hat{s}^{(i)}$$

$$\hat{p}^{(i+1)} = \hat{p}^{(i)} + \Delta \hat{p}$$

Where:

- $U = V^{-1}$, $U^{(0)} = 0$
- D is matrix of second derivatives: $D_{jk} = \frac{\partial^2 \log \mathcal{L}_\mu}{\partial \hat{p}_j \partial \hat{p}_k}$
- \hat{s} is vector of first derivatives: $\hat{s}_j = \frac{\partial \log \mathcal{L}_\mu}{\partial \hat{p}_j}$
- First and second derivatives are calculated numerically.

Alignment: convergence



Convergence test with
8 different misalignments

Precision scales as

$$\sigma_x \approx \frac{14 \text{ mm}}{\sqrt{n}}$$

$$\sigma_y \approx \frac{22 \text{ mm}}{\sqrt{n}}$$

$$\sigma_z \approx \frac{12 \text{ mm}}{\sqrt{n}}$$

$$\sigma_\alpha \sim \sigma_\beta \sim \sigma_\gamma \approx \frac{10 \text{ mrad}}{\sqrt{n}}$$

$$\sigma_t \approx \frac{75 \text{ ps}}{\sqrt{n}}$$

→ need $\mathcal{O}(10k)$ muons to
align a module

CPU: ~ 0.6 sec./iteration

Real time T0 calibration

The reference time is given by the accelerator RF clock signal - within some arbitrary offset to the interaction time (start time) that has to be determined from data.

Method

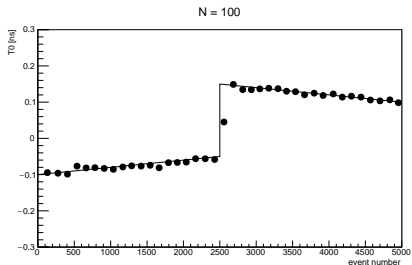
- With di-muon events (known PID, clean events, high momenta)
- Maximize sum of muon log likelihoods for offset T_0 :

$$\sum_{i=1}^N [\log \mathcal{L}_{\mu^+}^{(i)}(T_0) + \log \mathcal{L}_{\mu^-}^{(i)}(T_0)] = \max$$

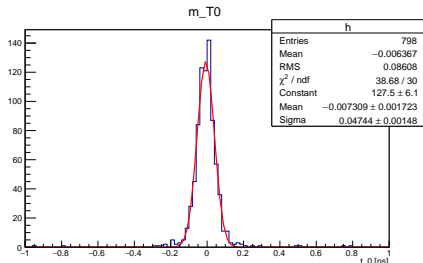
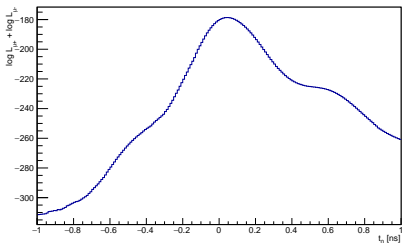
where N is the number of di-muon events and $\log \mathcal{L}_{\mu}$ are calculated with our standard analytic PDF based ext. likelihood method.

Real time T0 calibration

- Maximum is searched by performing a scan (local maxima sometimes present)
- Precision: ~ 50 ps for $N = 1$
- Need $\mathcal{O}(100)$ di-muon events to get down to ~ 5 ps
→ real time calibration possible



$N = 1$
di-muon log Likelihood vs. t_0



Conclusions

- We've presented the methods for alignment and time-offset calibration of the Belle II TOP counter.
- Channel offsets will be calibrated with a dedicated laser calibration system that is part of the TOP counter.
- For the module alignment an iterative procedure was developed and tested with MC simulation. It is based on minimization of negative log likelihoods of muons from $e^+e^- \rightarrow \mu^+\mu^-$ events; the log likelihoods are calculated with our standard analytic PDF's.
- Real time T0 calibration is found to be possible; this method is also based on muon log likelihoods from our standard likelihood calculation.