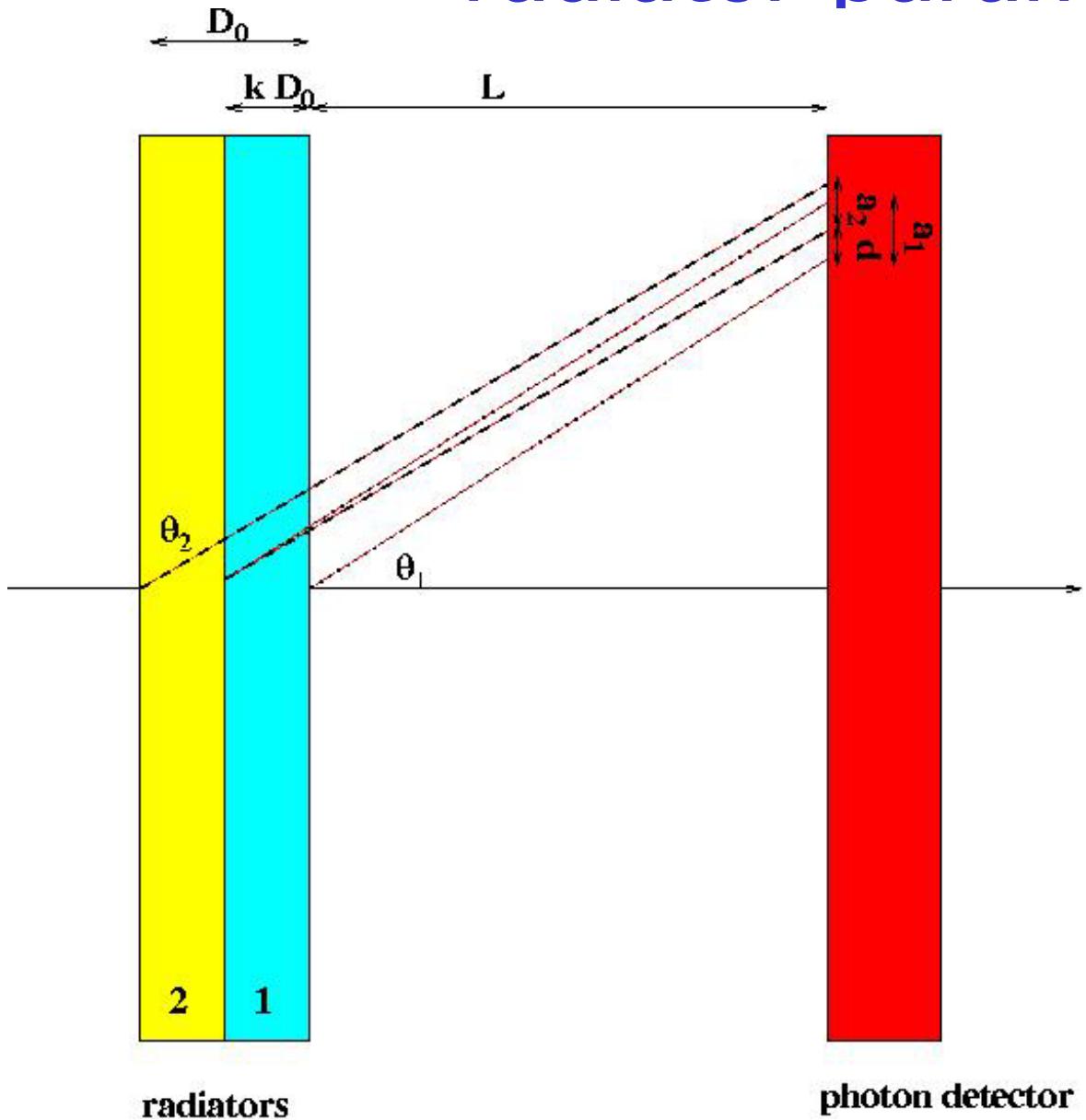


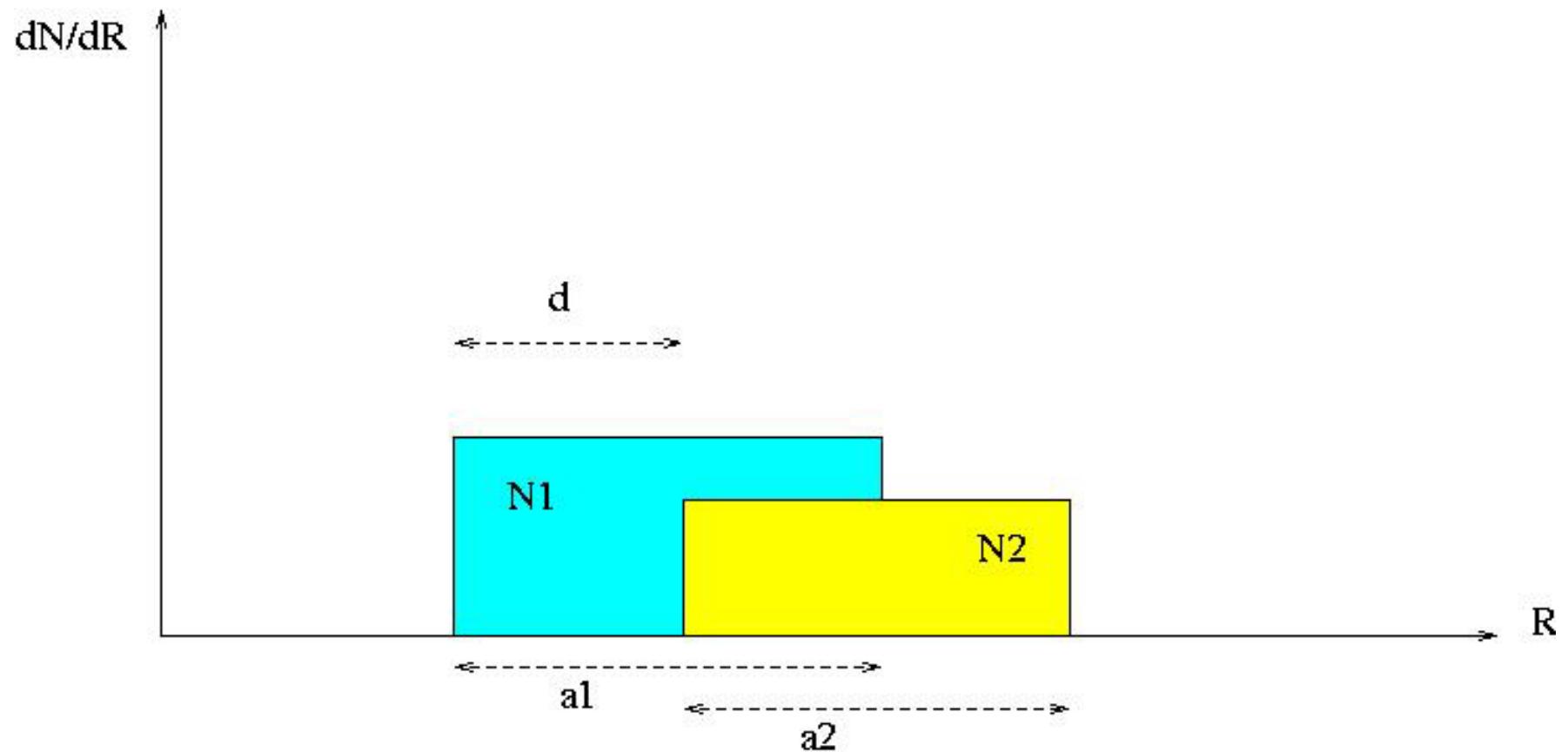
Multiple radiator: Optimisation of radiator parameters

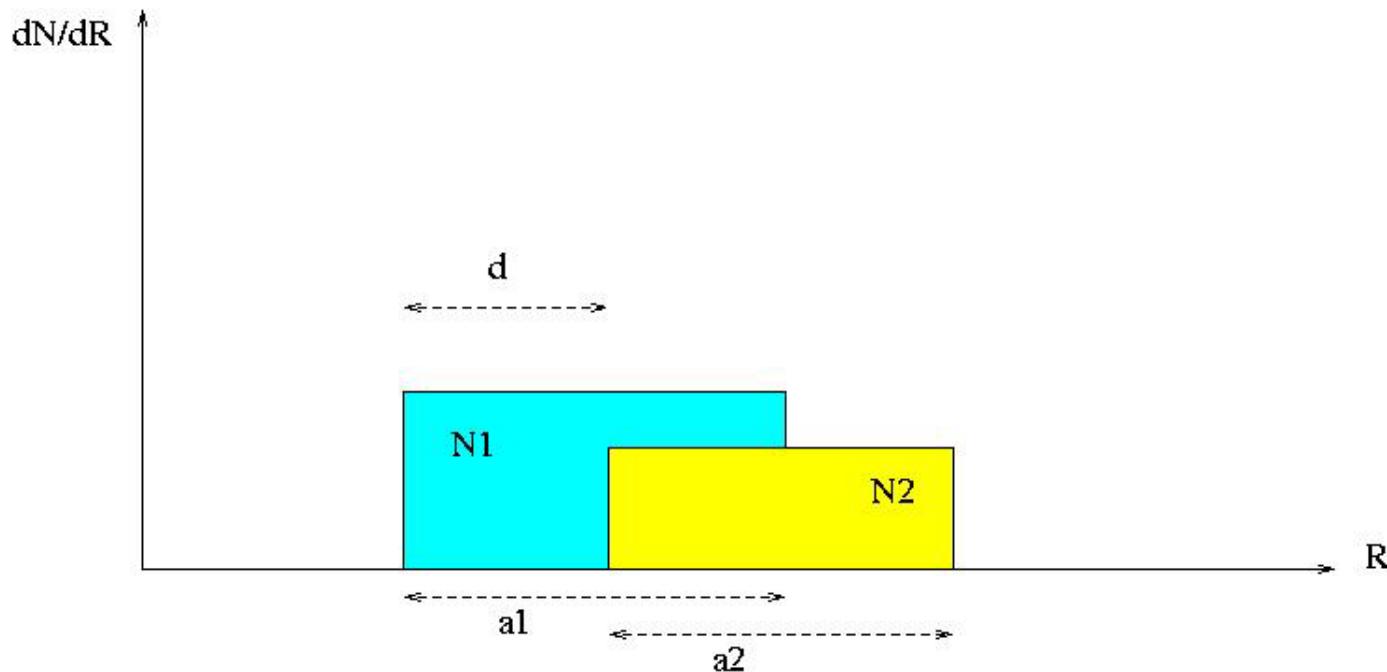


Dual radiator: three parameters (if fixed space available)

- Difference in θ
- Ratio of radiator thicknesses
- Total radiator thickness

Radial photon impact point distribution





$$\langle R \rangle = \frac{a_1 N_1 + (a_2 + 2d) N_2}{2 (N_1 + N_2)}$$

$$\langle R^2 \rangle = \frac{a_1^2 N_1 + (a_2^2 + 3a_2d + 3d^2) N_2}{3 (N_1 + N_2)}$$

$$\sigma_R^2 = \langle R^2 \rangle - \langle R \rangle^2 =$$

$$= -\frac{(a1 N1 + (a2 + 2 d) N2)^2}{4 (N1 + N2)^2} + \frac{a1^2 N1 + (a2^2 + 3 a2 d + 3 d^2) N2}{3 (N1 + N2)}$$

$$= \frac{1}{12 (N1 + N2)^2} (-3 (a1 N1 + (a2 + 2 d) N2)^2 + 4 (N1 + N2) (a1^2 N1 + (a2^2 + 3 a2 d + 3 d^2) N2))$$

$$\sigma_{R,\text{tot}}^2 = \sigma_R^2 + \sigma_{R,\text{padsize}}^2$$

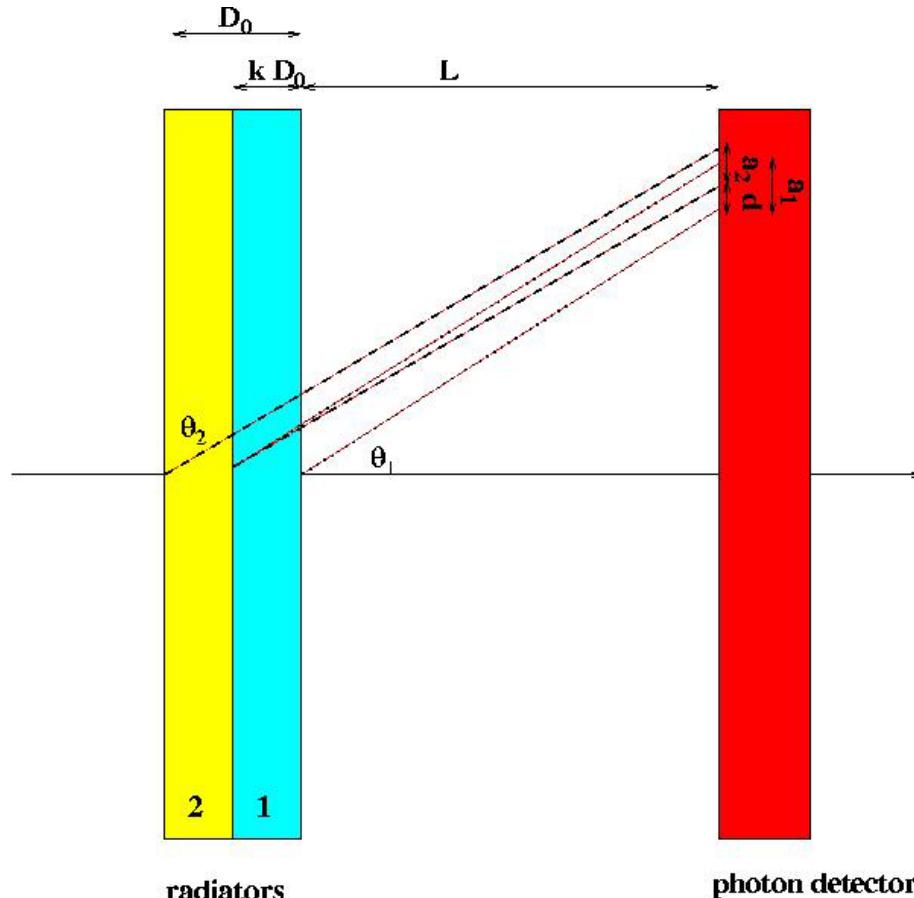
Parameters of the counter

$$a1 = D1 * \tan[\theta_1]; a2 = D2 * \tan[\theta_1 - \delta];$$

$$d = L * \tan[\theta_1] - (L + D1) * \tan[\theta_1 - \delta]; D1 = k * D0;$$

$$D2 = D0 - D1; N1 = 50 * D1 * (\sin[\theta_1])^2 * \exp[-D1 / 2 / \lambda_{m1}];$$

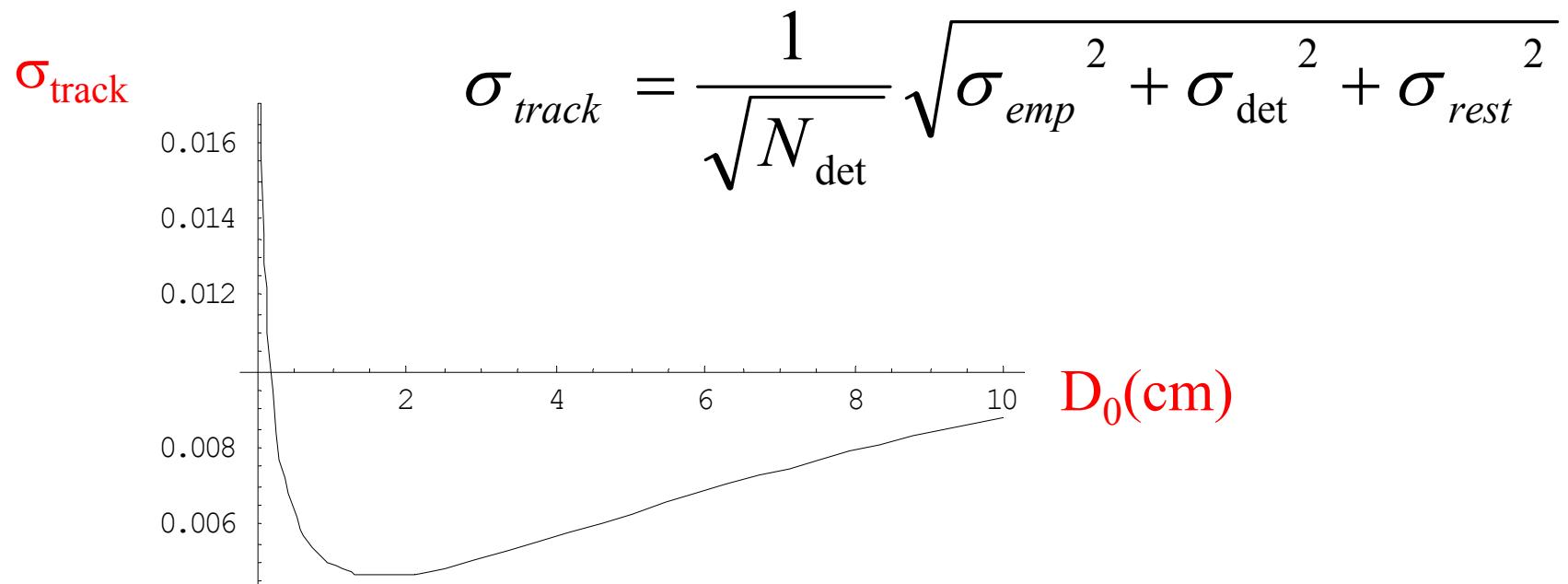
$$N2 = 50 * D2 * (\sin[\theta_1 - \delta])^2 * \exp[-D2 / 2 / \lambda_{m2} - D1 / \lambda_{m1}];$$



Check: plot track error vs. radiator thickness for the case both radiators have the same index

Input data:

- total length $L+D_0$ is fixed (20cm)
- attenuation length: 3cm
- Cherenkov angle = 0.3, pad size 6mm, $\sigma_{rest}=0$



Minimized: error per track

$$\sigma_{track} = \frac{1}{\sqrt{N_{det}}} \sqrt{\sigma_{emp}^2 + \sigma_{det}^2 + \sigma_{rest}^2}$$

Distance to photon detector

$$\frac{1}{(L + D_0 / 2)}$$

Number of photons

$$\sqrt{\left(\frac{1}{(N1 + N2)} \right)^2 + \sigma_{tot}^2}$$

Emission point error

$$\left(\frac{1}{12(N1 + N2)^2} \right)$$

$$(-3(a1 N1 + (a2 + 2d) N2)^2 +$$

$$4(N1 + N2) (a1^2 N1 + (a2^2 + 3 a2 d + 3 d^2) N2)) +$$

$$pad^2 / 12 \right))$$

Pad size contribution

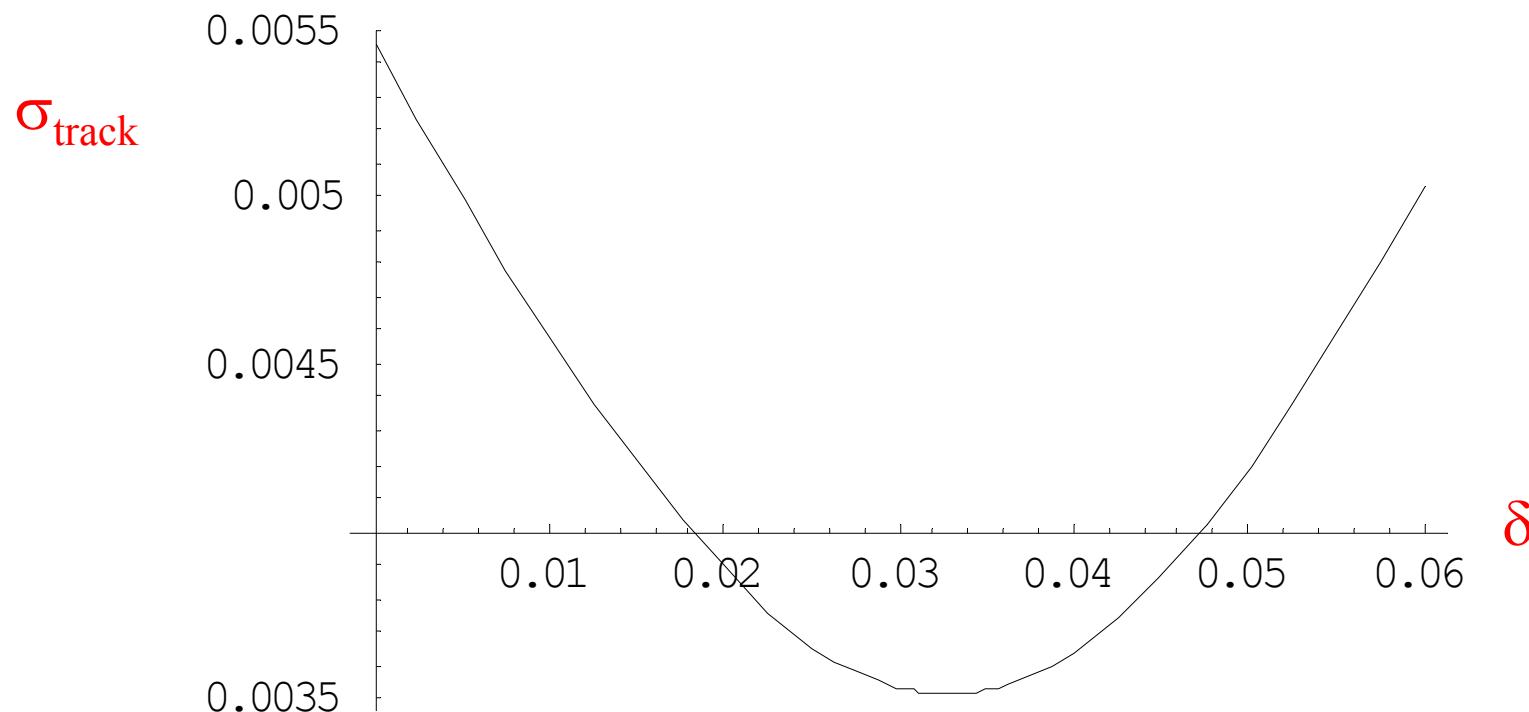
Until futher notice assume $\sigma_{rest}=0$

Vary Cherenkov angle difference δ

Track error vs. δ for the case both radiators have the same thickness ($k=0.5$)

Input data:

- total length $L+D_0$ is fixed (20cm), $D_0=4\text{cm}$
- Cherenkov angle = 0.3, pad size 6mm, no attenuation

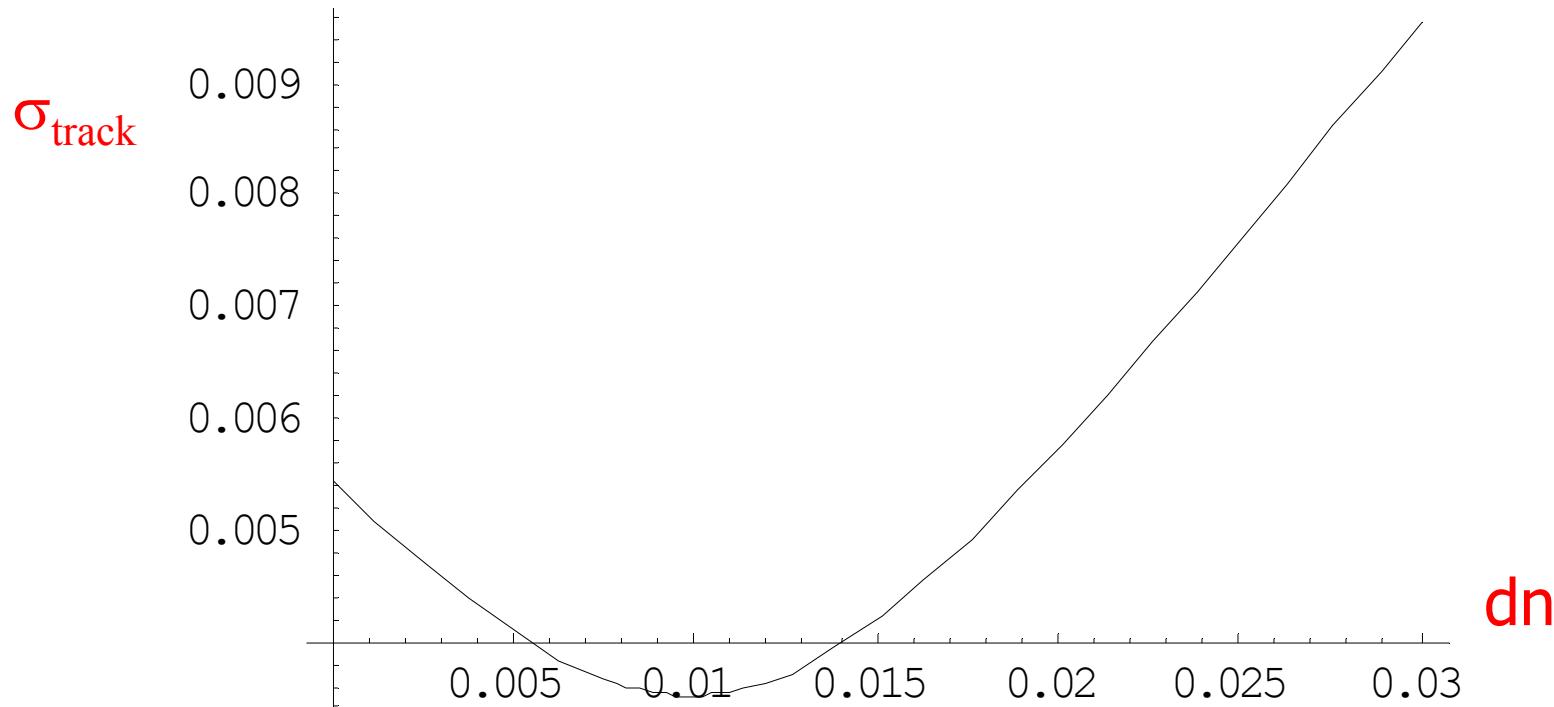


Vary refractive index difference dn

Track error vs. dn for the case both radiators have the same thickness ($k=0.5$)

Input data:

- total length $L+D_0$ is fixed (20cm), $D_0=4\text{cm}$
- Cherenkov angle = 0.3, pad size 6mm, no attenuation

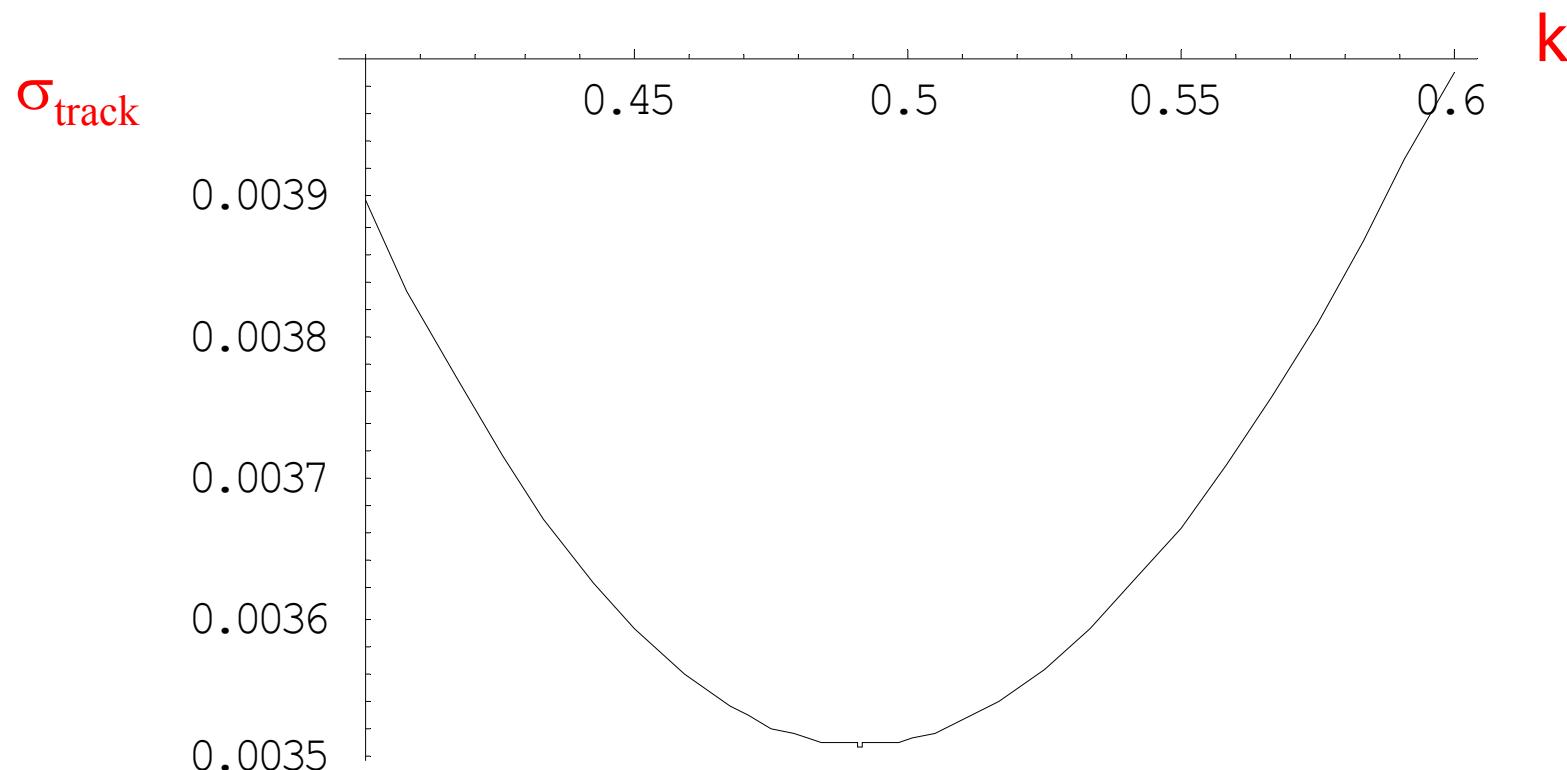


Vary relative radiator thickness k

Track error vs. k for the case $dn=0.01$

Input data:

- total length $L+D_0$ is fixed (20cm), $D_0=4\text{cm}$
- Cherenkov angle = 0.3, pad size 6mm, no attenuation

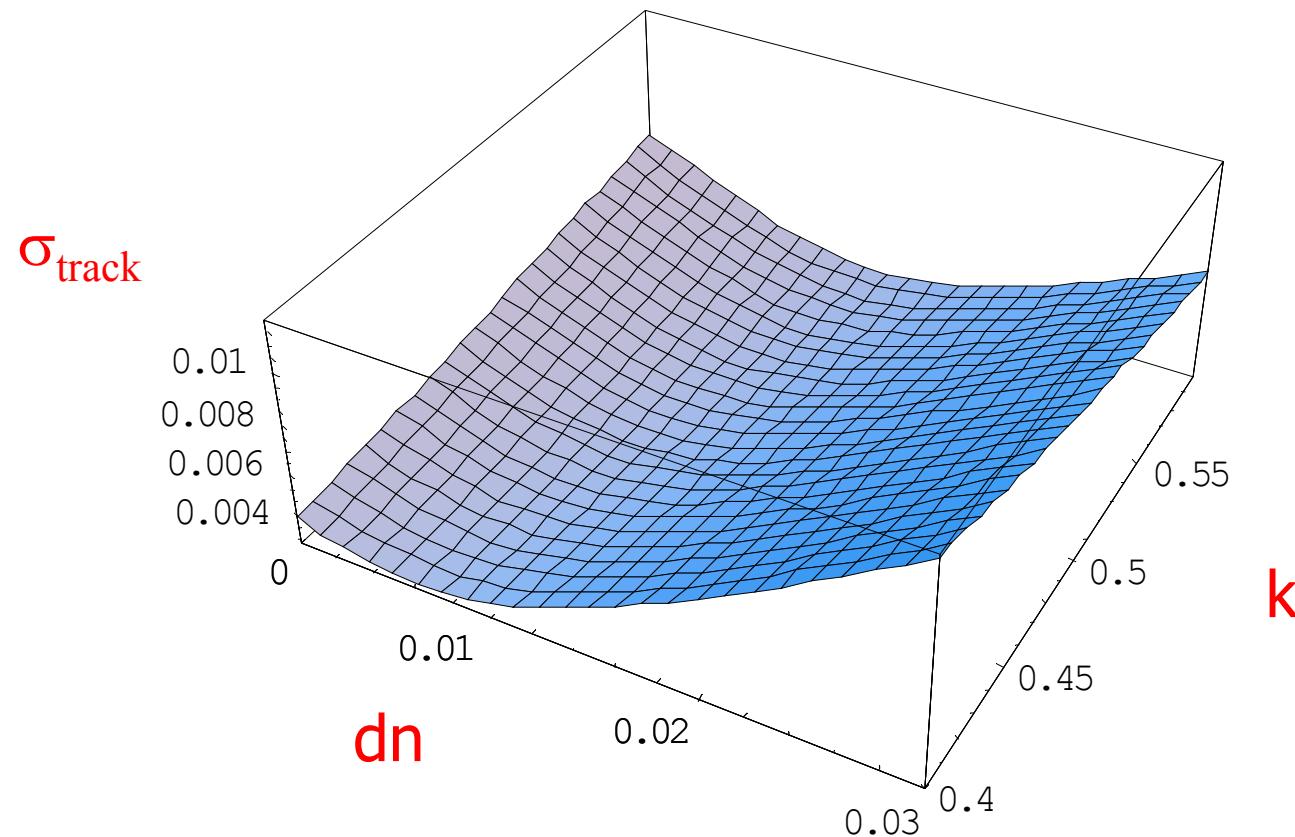


Vary radiator thickness k and refractive index difference dn

Track error vs. (k, dn) : correlation is no surprise

Input data:

- total length $L+D_0$ is fixed (20cm), $D_0=4\text{cm}$
- Cherenkov angle = 0.3, pad size 6mm, no attenuation



Minimize track error vs. radiator thickness k and refractive index difference dn , no attenuation

$dn=0.0082$

$k=0.455$

σ at minimum 0.0035

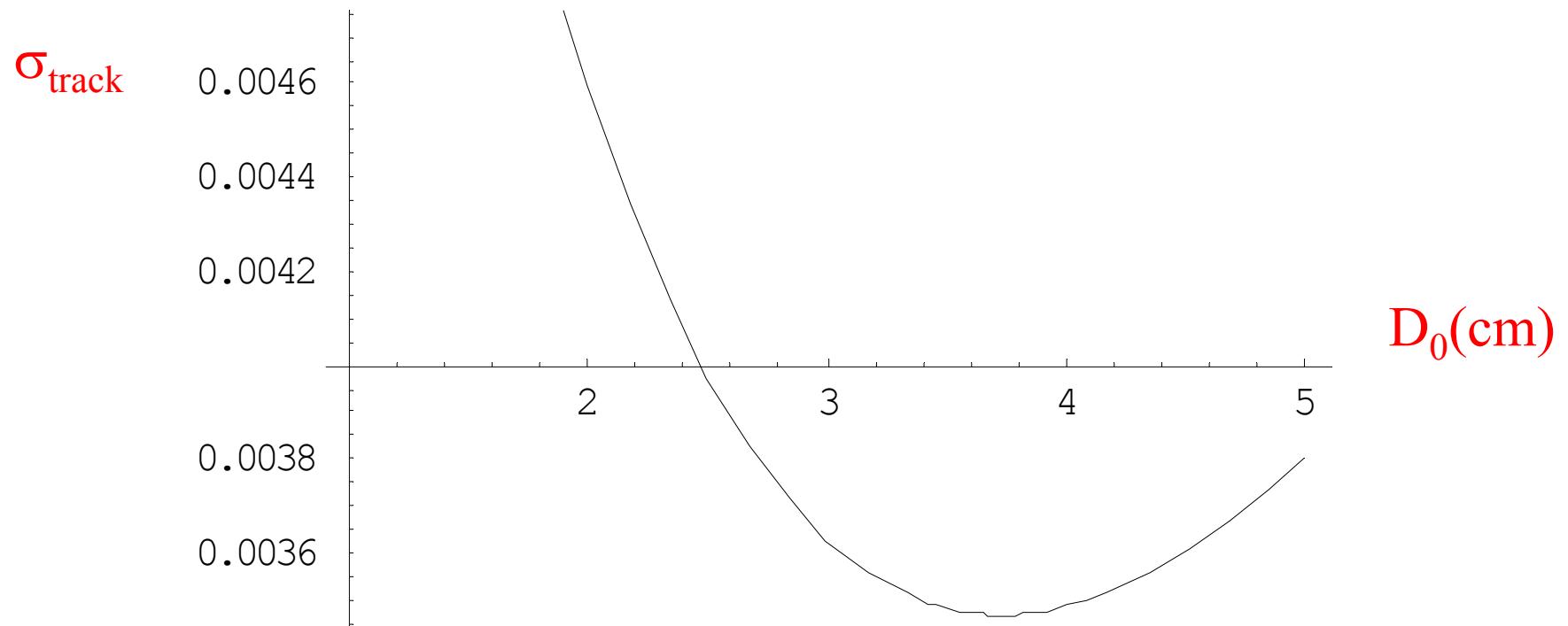
Very shallow minimum...

Vary total radiator thickness D_0

Track error vs. k for the case $dn=0.0082$, $k=0.455$

Input data:

- total length $L+D_0$ is fixed (20cm)
- Cherenkov angle = 0.3, pad size 6mm, no attenuation



Minimize track error vs. radiator thickness k and refractive index difference dn , attenuation lengths 3cm

$dn=0.007$

$k=0.42$

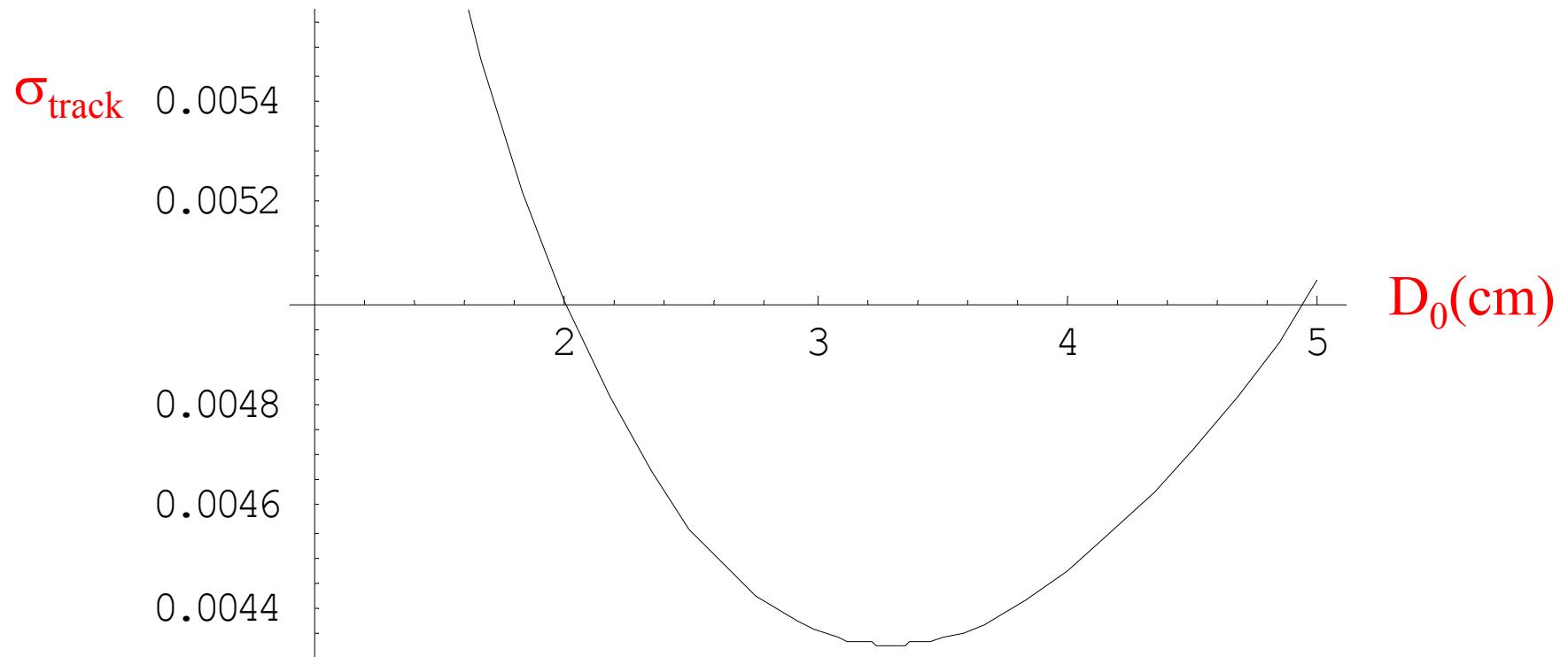
σ at minimum 0.0045

Vary total radiator thickness D_0

Track error vs. k for the case $\Delta n=0.007$, $k=0.42$

Input data:

- total length $L+D_0$ is fixed (20cm)
- Cherenkov angle = 0.3, pad size 6mm, attenuation lengths 3cm



Minimize track error vs.

radiator thickness k and refractive index difference dn and total thickness D_0

attenuation lengths 3cm

no attenuation

$dn=0.004$

$dn=0.006$

$k=0.44$

$k=0.46$

$D_0 = 2.35\text{cm}$

$D_0 = 3.1\text{cm}$

σ at minimum 0.0040

σ at minimum 0.0034

Available space in front of photon detector: **20cm**

Minimize track error vs.

radiator thickness k and refractive index difference dn and total thickness D_0

attenuation lengths 3cm

no attenuation

$dn=0.0034$

$dn=0.006$

$k=0.44$

$k=0.47$

$D_0 = 2.4\text{cm}$

$D_0 = 3.1\text{cm}$

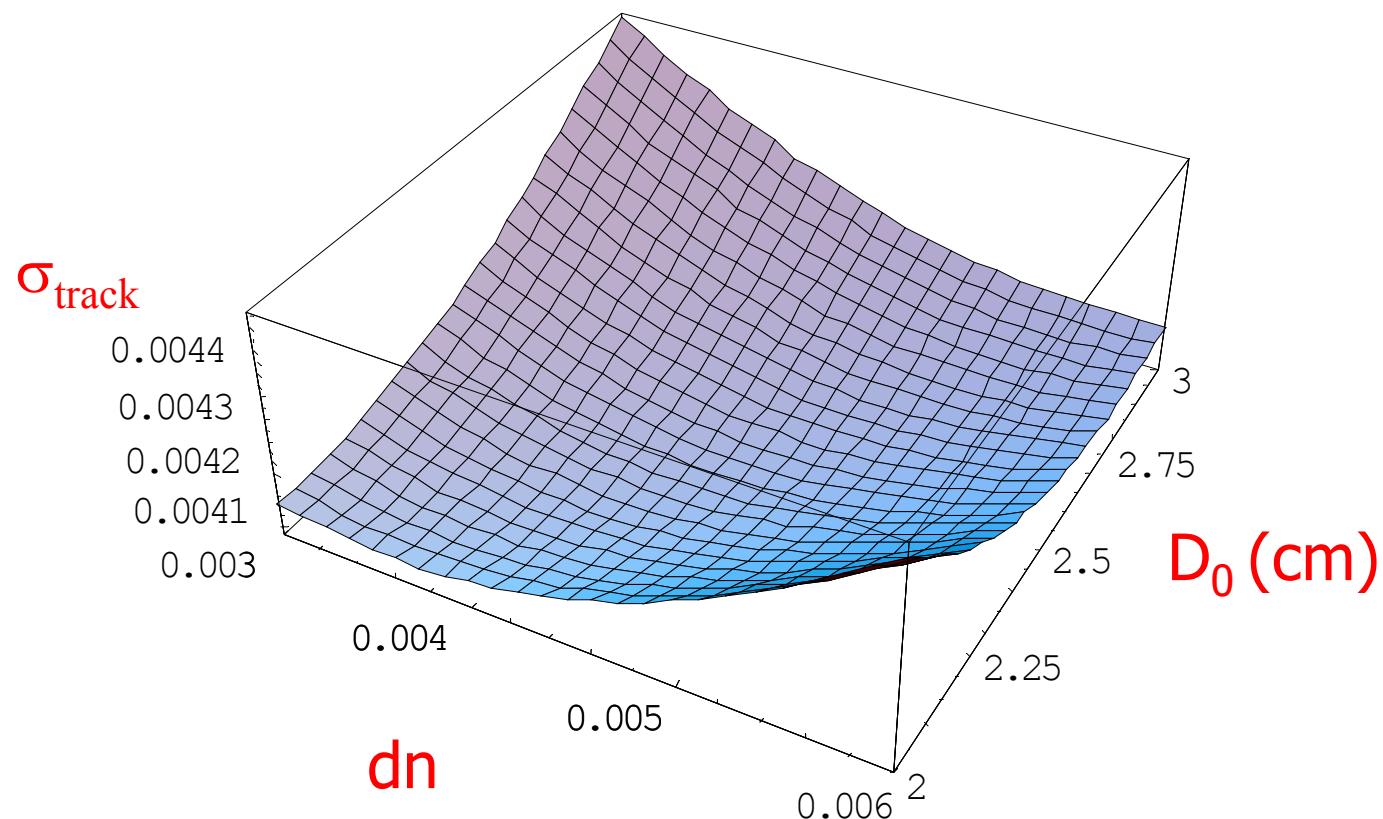
σ at minimum 0.0032

σ at minimum 0.0025

Available space in front of photon detector: **25cm**

Track error vs.

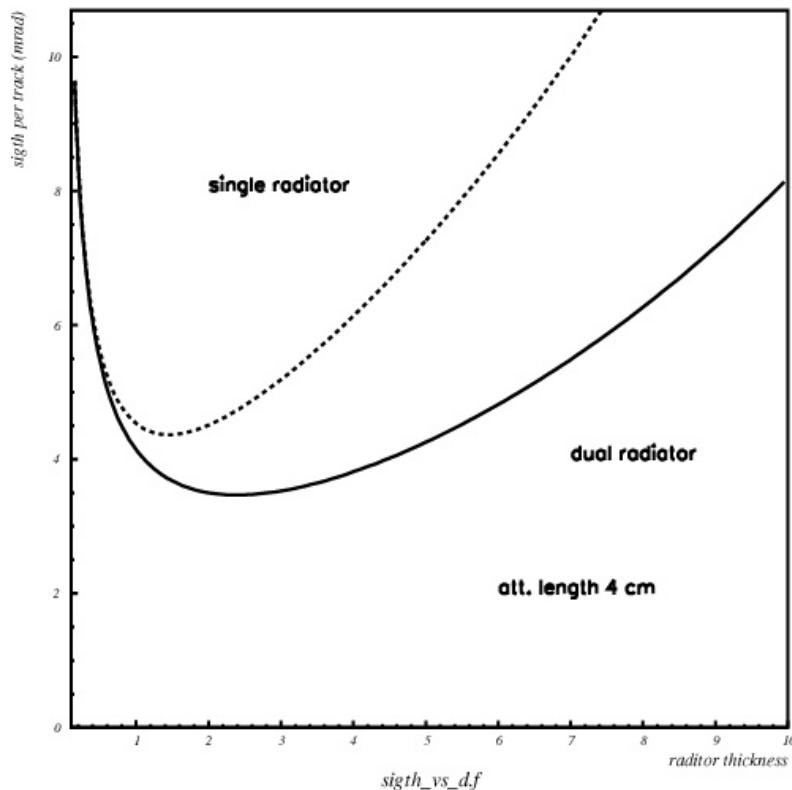
refractive index difference dn and total thickness D_0



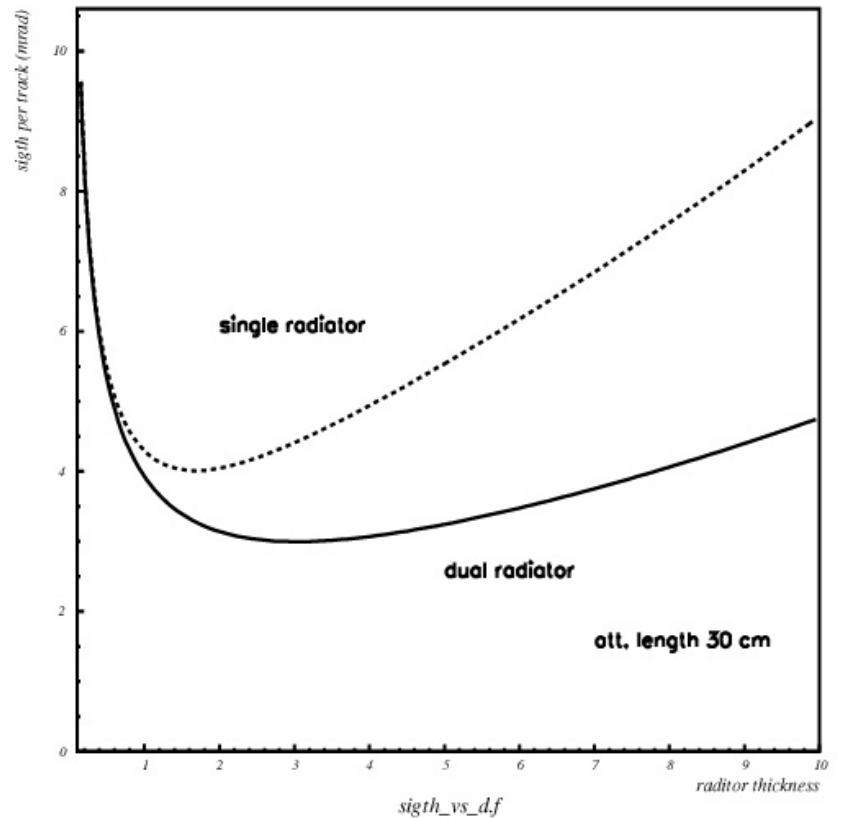
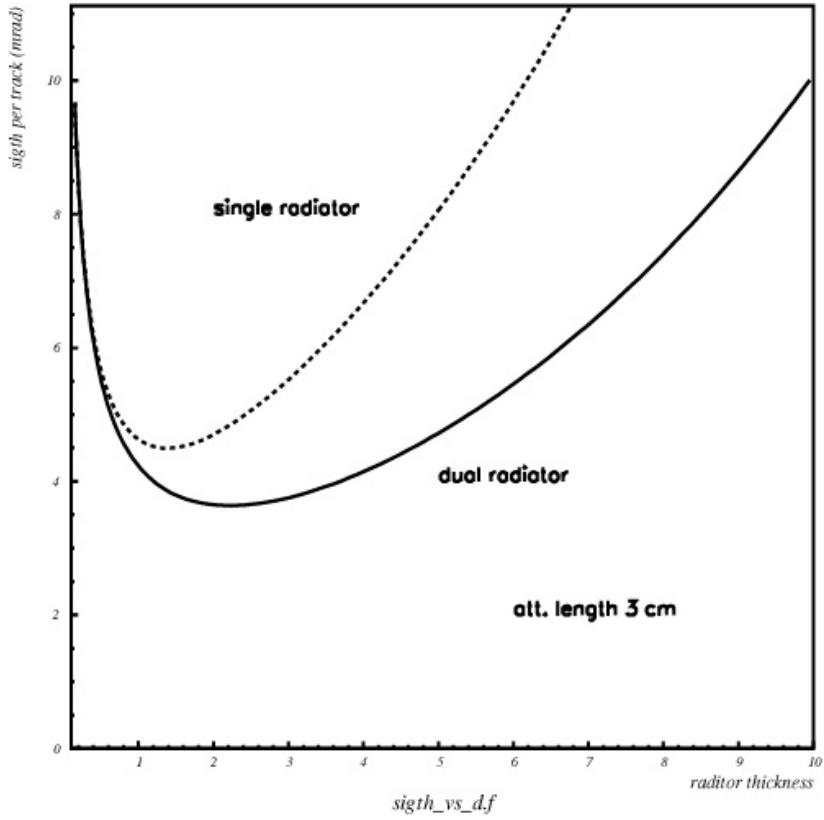
Can we make a simple model of what happens when we go from the single layer to focusing multilayer arrangement?

If the indices are well adjusted, the error in emission point **goes down by a factor of two** in the dual radiator case.

The **optimal thickness D_0 increases**.

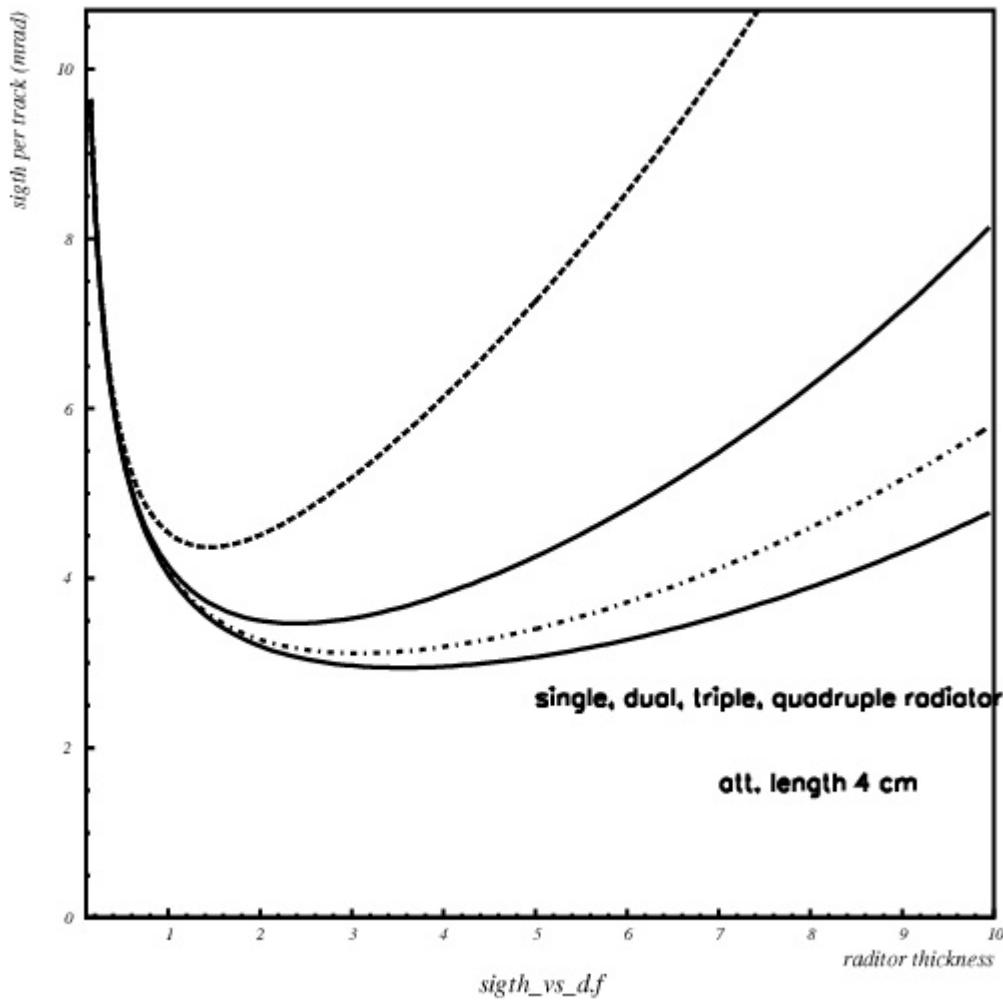


Simple model



Simple model

What happens if we increase the segmentation - number of layers?



Simple model

What happens if we take into account the
 $\sigma_{\text{rest}} = 7 \text{ mrad}$?

Expect that the minimum in σ_{track} will come later, at higher values of radiator thickness D_0 .

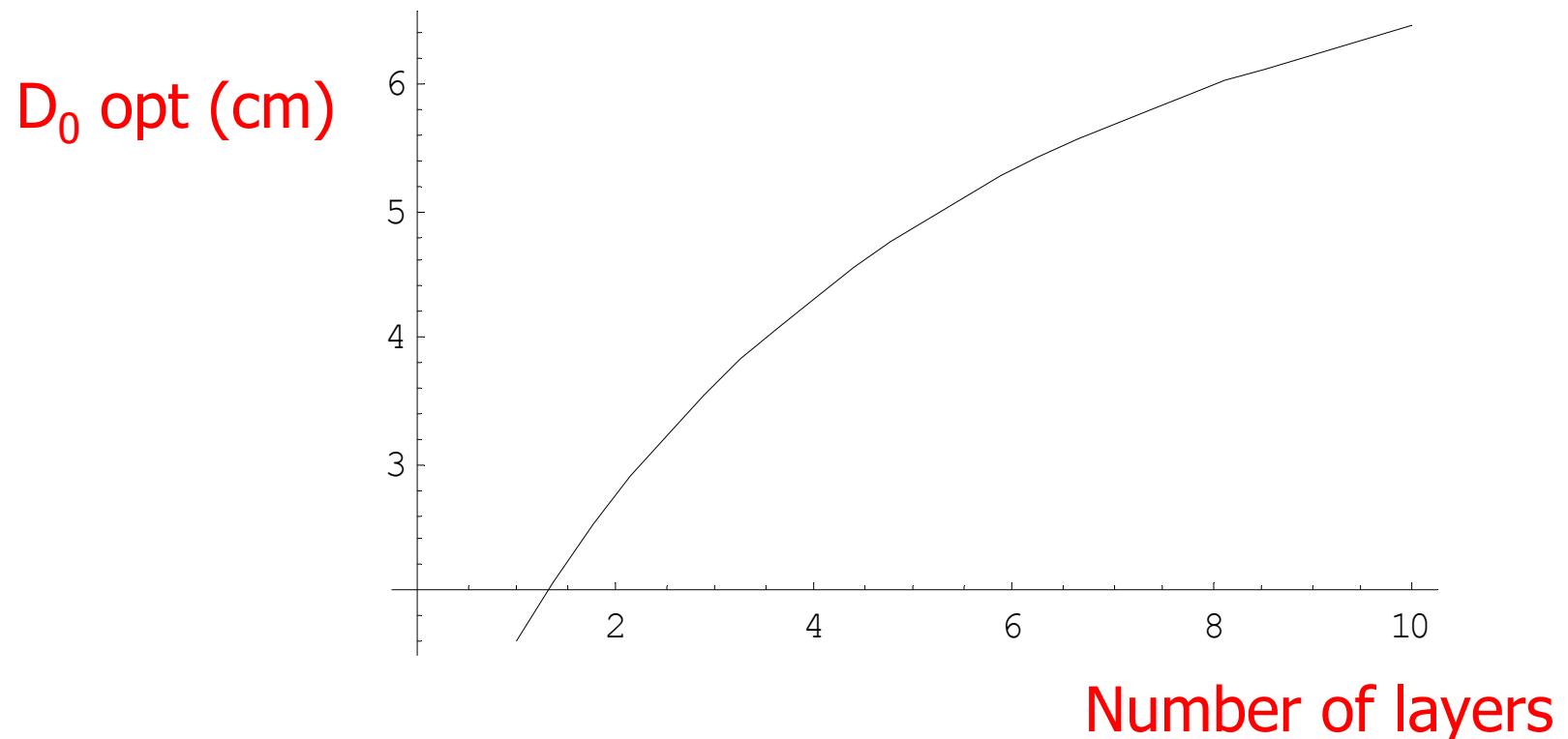
Find the minimum of σ_{track} vs D_0 as a function of the number of layers x .

Plot D_0 vs x .

$$\begin{aligned}
D_0^{\text{opt}} = & -\frac{2 \text{Lam}}{3} - \\
& \left(2^{1/3} \csc[\Theta]^2 \sec[\Theta]^2 (3x^2 \cos[\Theta]^2 (12 \text{Lsigre}^2 + a^2 \cos[\Theta]^4) \right. \\
& \quad \left. \sin[\Theta]^2 - 4 \text{Lam}^2 \cos[\Theta]^4 \sin[\Theta]^4) \right) / \\
& (3 (864 \text{L Lam sigre}^2 x^2 \cos[\Theta]^4 \sin[\Theta]^4 + 72 a^2 \text{Lam} x^2 \\
& \quad \cos[\Theta]^8 \sin[\Theta]^4 - 16 \text{Lam}^3 \cos[\Theta]^6 \sin[\Theta]^6 + \\
& \quad \sqrt{(4 (3x^2 \cos[\Theta]^2 (12 \text{Lsigre}^2 + a^2 \cos[\Theta]^4) \sin[\Theta]^2 - \\
& \quad 4 \text{Lam}^2 \cos[\Theta]^4 \sin[\Theta]^4)^3 + (864 \text{L Lam sigre}^2 \\
& \quad x^2 \cos[\Theta]^4 \sin[\Theta]^4 + 72 a^2 \text{Lam} x^2 \cos[\Theta]^8 \\
& \quad \sin[\Theta]^4 - 16 \text{Lam}^3 \cos[\Theta]^6 \sin[\Theta]^6)^2})^{1/3}) + \\
& \frac{1}{3^{21/3}} (\csc[\Theta]^2 \sec[\Theta]^2 (864 \text{L Lam sigre}^2 x^2 \cos[\Theta]^4 \sin[\Theta]^4 + \\
& \quad 72 a^2 \text{Lam} x^2 \cos[\Theta]^8 \sin[\Theta]^4 - 16 \text{Lam}^3 \cos[\Theta]^6 \sin[\Theta]^6 + \\
& \quad \sqrt{(4 (3x^2 \cos[\Theta]^2 (12 \text{Lsigre}^2 + a^2 \cos[\Theta]^4) \sin[\Theta]^2 - \\
& \quad 4 \text{Lam}^2 \cos[\Theta]^4 \sin[\Theta]^4)^3 + (864 \text{L Lam sigre}^2 \\
& \quad x^2 \cos[\Theta]^4 \sin[\Theta]^4 + 72 a^2 \text{Lam} x^2 \cos[\Theta]^8 \\
& \quad \sin[\Theta]^4 - 16 \text{Lam}^3 \cos[\Theta]^6 \sin[\Theta]^6)^2})^{1/3})
\end{aligned}$$

Simple model

How does the optimal thickness D_0 depend on the number of layers?



$\sigma_{\text{rest}} = 7 \text{ mrad}$, fixed: distance aerogel–photon detector,
att.len.=4cm

Simple model

What comes next?

- Repeat the optimisation study with σ_{rest}
- Extend the full calculation to the **multilayer** case
- Study the robustness of the optimum